Position control unit

Point-to-point positioning controller with pulse train output and motion control unit functionality

- · Position control units with 2 or 4 axes
- · Position and speed control
- Linear interpolation and feeder control function
- · Electronic CAM profiles and axes synchronization
- Positioning of 500 points per axis done from memory
- S-curve acceleration/deceleration, origin search, backlash compensation, and other features are also supported.
- Programming languages: ladder, function blocks.
- Use Windows-based support software to easily create positioning data and store data and parameters in files.



Function

These position control units support positioning control via pulse-train outputs. Positioning is performed using trapezoidal or Scurve acceleration and deceleration. Models are available with 2 or 4 axes control, and can be used in combination with servo drives or stepping motors what accept pulse-train control. When these units are used in a CJ2 PLC CPU can perform also synchronous operation by use of electronic CAMs and other function blocks.

System configuration



Specifications

Model		CJ1W-NC214	CJ1W-NC414	
		CJ1W-NC234	CJ1W-NC434	
Unit name		Position control unit		
Classification		CJ series special I/O units		
Applicable PLCs		CJ series		
Unit numbers		0 to 94		
Maximum number of units per rack		5 units		
Maximum number of units per CJ system		20 units (3 expansion racks maximum)		
Occupied unit		2		
Control method		Open-loop control by pulse train output		
Control output signals		CJ1W-NC□14: Open-collector output		
		CJ1W-NC□34: Line-driver output		
Controlled axes		2	4	
I/O allocations	Axis operating memory area	0	areas(user-specified): CIO, WR, HR, DM or EM area.	
Control function	Operating modes	Direct operation or memory operation		
	Linear interpolation	2 axes maximum	4 axes maximum	
	Circular interpolation	2 axes maximum		
	Interrupr feeding	Independent, 2 axes	Independent, 4 axes	
	Position data	-2147483648 to +2147483647		
	No. of positions	500 per axis		
	Speed data	4 Mpps maximum speed (NC234/434) or 500 kpps (NC214/414)		
	No. of speeds	500 per axis		
	Acceleration/deceleration times	0 to 250 s (time to max. speed)		
	Acceleration/deceleration curves	Trapezoidal or S-curve		
Auxiliary functions	Override	Multiplies the axis command speed by a specified ratio. Value: 0.01% to 500.00%		
	Sofware limits	Limits software operation for controlling positioning		
	Backlash compensation	Compensates for the amount of play in the mechanical system according to a set value		
	Torque limit	Restrics the torque upper limit during position control		
Saving data in PCU		Flash memory		
Ambient operating temperature		0 to 55°C		
External power supply		24 VDC		
Internal current consumption		270 mA or less at 5 VDC	310 mA or less at 5 VDC	
Weight		170 g	220 g	

Nomenclature

CJ1W-NC214/234/414/434 - position control unit



Dimensions

CJ1W-NC214/234/414/434 - position control unit





Ordering information

Position control unit

Name	Model
2 axes position control unit. Open-collector output.	CJ1W-NC214
4 axes position control unit. Open-collector output.	CJ1W-NC414
2 axes position control unit. Line-driver output.	CJ1W-NC234
4 axes position control unit. Line-driver output.	CJ1W-NC434

Servo drive cables

Note: Refer to selected servo systems section for cable and servo relay units information.

Computer software

Specifications	Model
CX-One version 4.0 or higher	CX-One

ALL DIMENSIONS SHOWN ARE IN MILLIMETERS.

To convert millimeters into inches, multiply by 0.03937. To convert grams into ounces, multiply by 0.03527.

Cat. No. I77E-EN-01B

In the interest of product improvement, specifications are subject to change without notice.