



- Large measuring range (standard measuring length up to 100 m $^{1)}\mbox{)}.$
- Usable for linear and rotary movements.
- Incremental or absolute measurement.
- All usual interfaces/field buses.
- Application-specific adaptation of the spring encoder arm (adjustable pressing force).
- Compensation of application tolerances.

- Simple mounting.
- Steel-reinforced plastic belt.
- Robust Sendix encoders.
- Wide temperature range of -25°C ... +80 °C.
- High traversing speed up to 5 m/s.

Single components Limes Kit TB1: 8.0010 . 7000 . 0010 Spring encoder arm (See the table of recommended encoders) Encoder All incremental or absolute Sendix encoders with clamping flange (centering collar 36 mm) and 10 mm shaft diameter (shaft 10x20 mm) can be used. Preferred types with short delivery time are shown in **bold underlined** Pulley XXXX 8.0000 AXX1 **a b** C **a** Material **b** Width C Pitch circumference C Other pitch circumferences on request = 10 mm [0.39"] 0300 = 300 mm0150 = 150 mm1 = aluminum 0360 = 360 mm 2 = plastic 2 = 20 mm [0.79"] 0240 = 240 mm 0120 = 120 mm 0220 = 220 mm 0100 = 100 mmPreferred types with short delivery time are shown in **bold underlined** Toothed belt 8.0000 B1X1 XXXX 0 0 Width **b** Length [in dm] ¹⁾, ex.: Ontional on request: 1 = 10 mm [0.39"]0010 = 1 m [3.28'] length > 100 m 3 = 25 mm [0.94"]0020 = 2 m [6.56'] 4 = 50 mm [1.97"]1000 = 100 m [328']

1) Yard ware (1 m, 2 m, ... 100 m), lengths > 100 m on request.



Length measuring kitStandard measuring length up to 100 mwith spring encoder armLimes Kit TB1Application-specific adaptation

Recommended encoders, incremental

Encoder	Interface	Power supply	Type of connection	Pulley circumference [mm]	Recommended encoder resolution (pulse number)	mm / pulse	Order no.
Sendix 5000	push-pull with	10 30 V DC	1 x radial M12 connector	360	3600	0.1	8.5000.8354.3600
	inverted signal			300	3000	0.1	8.5000.8354.3000
				240	240	1.0	8.5000.8354.0240
				220	2500	0.088	8.5000.8354.2500
				150	1500	0.1	8.5000.8354.1500
				120	1200	0.1	8.5000.8354.1200
				100	1000	0.1	8.5000.8354.1000

Recommended encoders, absolute

Encoder	Interface	Power supply	Type of connection	Resolution / Protocol	Option	Order no.
Sendix M5861	analog, 4 20 mA	10 30 V DC	1x radial M12 connector	12 bit (4096)	scalable with limit switch function	8.M5861.3534.3312
	analog, 0 10 V	10 30 V DC	1x radial M12 connector	12 bit (4096)	scalable with limit switch function	8.M5861.3544.4312
	analog, 0 5 V	10 30 V DC	1x radial M12 connector	11 bit (2048)	scalable with limit switch function	8.M5861.3544.5312
Sendix M5863	SSI	10 30 V DC	1x radial M12 connector	4096 ppr / SSI Gray code	-	8.M5863.3524.G222
Sendix M5868	CANopen	10 30 V DC	1x radial M12 connector	CANopen encoder profil DS406 V4.0	-	8.M5868.3524.2122

Further encoders, absolut

Encoder	Interface	Power supply	Type of connection	Resolution / Protocol	Option	Order no.
Sendix F5863	SSI	10 30 V DC	1x radial M12 connector	4096ppr / SSI Gray code	SET button + status LED	8.F5863.1226.G223
Sendix 5863	SSI	10 30 V DC	1x radial M12 connector	4096ppr / SSI Gray code	SET button + status LED	8.5863.1226.G233
Sendix F5868	CANopen	10 30 V DC	1x radial M12 connector	CANopen encoder profil DS406 V3.2	SET button	8.F5868.122E.2123
Sendix 5868	CANopen	10 30 V DC	2x radial M12 connector	CANopen encoder profil DS406 V3.2	SET button	8.5868.1222.2123
Sendix 5868	PROFIBUS	10 30 V DC	3x radial M12 connector	Profibus-DP V0 encoder profil class 2	SET button	8.5868.1232.3113
Sendix 5868	EtherCAT	10 30 V DC	3x radial M12 connector	EtherCAT with CoE 3.2.10	-	8.5868.12B2.B212
Sendix 5868	PROFINET IO	10 30 V DC	3x radial M12 connector	PROFINET encoder profil version 4.1	-	8.5868.12C2.C212
Sendix F5868	EtherNet/IP	10 30 V DC	3x radial M12 connector	EtherNet/IP	-	8.F5868.12AN.A222



Length measuring kit with spring encoder arm	Limes Kit TE			J length up to 100 m c adaptation	
Technical data					
Total system		Pulley			
Temperature range	-25°C +80°C [-13°F +176°F]	Material	alum	inum or plastic (POM-C)	
Max. traversing speed	5 m/s	Width	10/2	20 mm	
IP protection	depends on the encoder used	Pitch circumfere	nce 100 .	360 mm	
	(refer to the encoder data sheet)	Number of teeth	20	72	
		Toothing type		HD60 – 5M	
Spring encoder arm		Pitch	5 mn	1	
Material	aluminum				
Spring force = maximum pressing force	max. 40 N	Toothed belt			
on the toothed belt		Material		-reinforced PU with polyamide	
Minimum pressing force of the pulley	min. 20 N		fabri	c on the teeth side	
on the toothed belt	(ca. 20 N = 1 notch/position)	Adhesive basis	Mod	ified acrylate	
		Toothing type	RTD	5M	
		Tooth strength	37.8	N/cm belt width	
Encoder		Bend radius	min.	30 mm	
Technical data	depends on the encoder used (refer to the encoder data sheet)	Width		m, 25 mm, 50 mm ers on request)	
Flange type	All encoders with clamping flange	Height	3.8 m	im	
	(centering collar 36 mm) and 10 mm shaft can be used	Length tolerance	± 0.8	mm/m	
	Shure oull be used	Width tolerance	± 0.5	mm	
		Weight	10 mm width 40 g/ 25 mm width 100 g 50 mm width 195 g	ı/m	

Technic in detail

Overview belt pulley

Number of teeth	Pitch [mm]	mm] in mm ["]	Pitch diameter ¹⁾ in mm ["] (pitch x no of teeth) / π	Pitch circumference in mm (pitch x no of teeth) or	Order no. B = pulley width x = material (1 = aluminum, 2 = plastic)		
				(Pitch diameter x π)	B = 10 mm	B = 20 mm	
72	5	113.45 [4.47]	114.59 [4.51]	360	8.000.Ax11.0360	8.000.Ax21.0360	
60	5	94.35 [3.71]	95.49 [3.76]	300	8.000.Ax11.0300	8.000.Ax21.0300	
48	5	75.25 [2.96]	76.39 [3.01]	240	8.000.Ax11.0240	8.000.Ax21.0240	
44	5	68.89 [2.71]	70.03 [2.76]	220	8.000.Ax11.0220	8.000.Ax21.0220	
30	5	46.61 [1.84]	47.75 [1.88]	150	8.000.Ax11.0150	8.000.Ax21.0150	
24	5	37.06 [1.46]	38.19 [1.50]	120	8.000.Ax11.0120	8.000.Ax21.0120	
20	5	30.69 [1.21]	31.83 [1.25]	100	8.000.Ax11.0100	8.000.Ax21.0100	

Resolution examples with encoder (incremental / absolut)

Incremental encoder Sendix 5000						
Pitch circumference [mm]	360	360				
Pulses / revolution [ppr]	360	3600				
Pulses / mm	1	10				
Resolution	1	0.1				

Absolut encoder Sendix 5863 (12 bit ST) or M5868 (12 bit ST, programmable via bus)						
Pitch circumference [mm]	360					
Pulses / revolution [ppr]	4096					
Pulses / mm	~ 11.5					
Resolution	~ 0.088					

1) The pitch diameter of the pulley is always larger than the diameter of the pulley, as the height of the belt must be considered





- 1 Set screw M5 DIN913 (SW2,5) recommended tightening torque 2.0 Nm
- 2 3 M3x8 DIN912 (SW2.5) screws recommended tightening torque 2.0 Nm (attached)
- 3 Setting with a screwdriver size 0 or 1
- 4 M8x60 DIN912 (SW6) screws
- 5 Spacer disk

- Proceed as follows to adjust the required pressing force ${\bf F}$ (pulley / toothed belt):
- 1. Loosen screw 4 (SW6) on the spring encoder arm.
- 2. Adjust the required angle of the spring encoder arm.
- 3. Turn adjusting wheel ${\bf E}$ to set the required pressing force ${\bf F}$ (max. 2 positions $\,\hat{=}\,$ 40 N).
- 4. Tighten screw $\fbox{4}$ (SW6) on the spring encoder arm (recommended torque 20 Nm).





Width toothed belt A	Width pulley B	No of teeth	Pitch diameter ø Dw	Tooth geometry øDz ^{+0,1}	Distance to toothed belt R ±1
	10 [0.39] 20 [0.79]	72	114.59 [4.51]	113.45 [4.47]	58.6 [2.31]
		60	95.49 [3.76]	94.35 [3.71]	49.0 [1.93]
10 [0.39]		48	76.39 [3.01]	75.25 [2.96]	40.9 [1.61]
25 [0.98]		44	70.03 [2.76]	68.89 [2.71]	36.3 [1.43]
50 [1.97]		30	47.75 [1.88]	46.61 [1.84]	25.1 [0.99]
		24	38.19 [1.50]	37.06 [1.46]	20.4 [0.80]
		20	31.83 [1.25]	30.69 [1.21]	17.2 [0.68]

C = see encoder data sheet

L = yard ware (1 m, 2 m, ... 100 m)

other lengths > 100 m on request